

Project Resources



CS 598: Embodied Task Oriented Dialogue

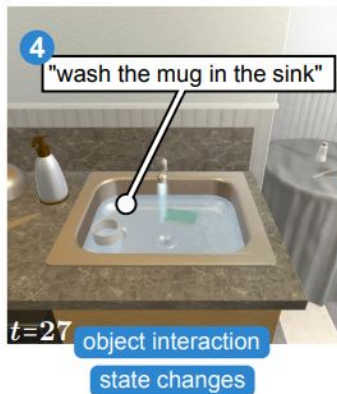
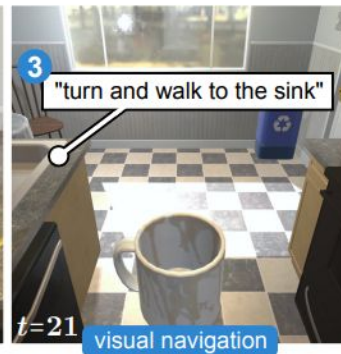
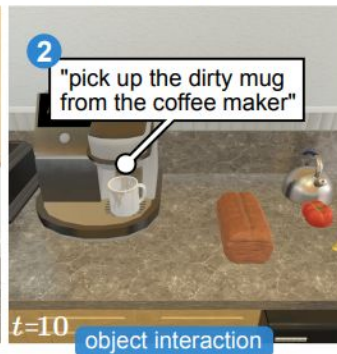
AI2THOR

- interactive environments for embodied AI
- simulation
 - physics, lighting, material, layouts
- household environments
 - kitchen, bedroom, bathroom, etc
- object interactions
 - track states
- demo
- documentation
- colab starter

Datasets (ALFRED)

- embodied task completion
 - object interaction
 - state changes
- simulated environment
- natural language instructions
- metrics
 - task success
 - goal condition success
 - path weighted metrics
 - sub-goal evaluation
- CVPR'21

Goal: "Rinse off a mug and place it in the coffee maker"





Annotation # 1

Goals

Put a clean rag on the top shelf of a barred rack.

Instructions

Turn around, go to the barred rack. Pick up the rag from the bottle shelf of the barred rack. Go to the sink on the left. Put the rag in the sink, turn on then turn off the water. Go to the barred rack to the right of the sink. Put the rag on the top shelf of the barred rack.

Annotation # 2

Wash the pink towel on the shelf, put it back on the shelf.

Wash the pink towel on the shelf, put it back on the shelf. Turn around and go the shelf. Pick up the pink towel on the shelf. Turn around and put the towel in the sink. Fill the sink with water and wash the towel, take the towel out. Go back to the shelf. Put the towel back on the shelf.

Annotation # 3

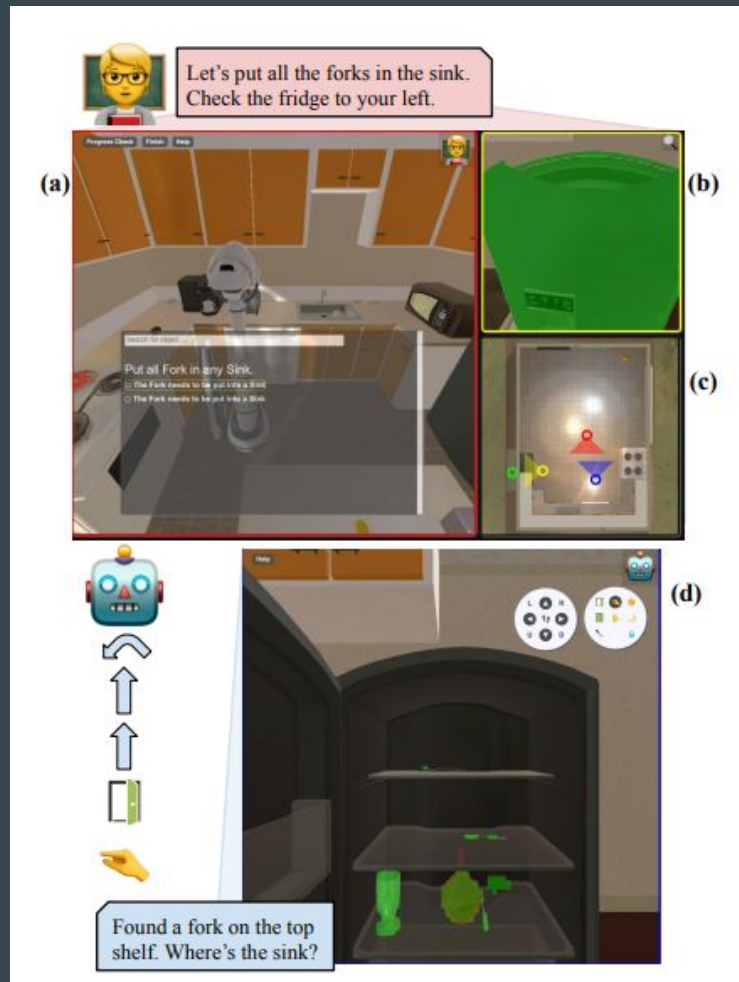
Clean a red cloth.

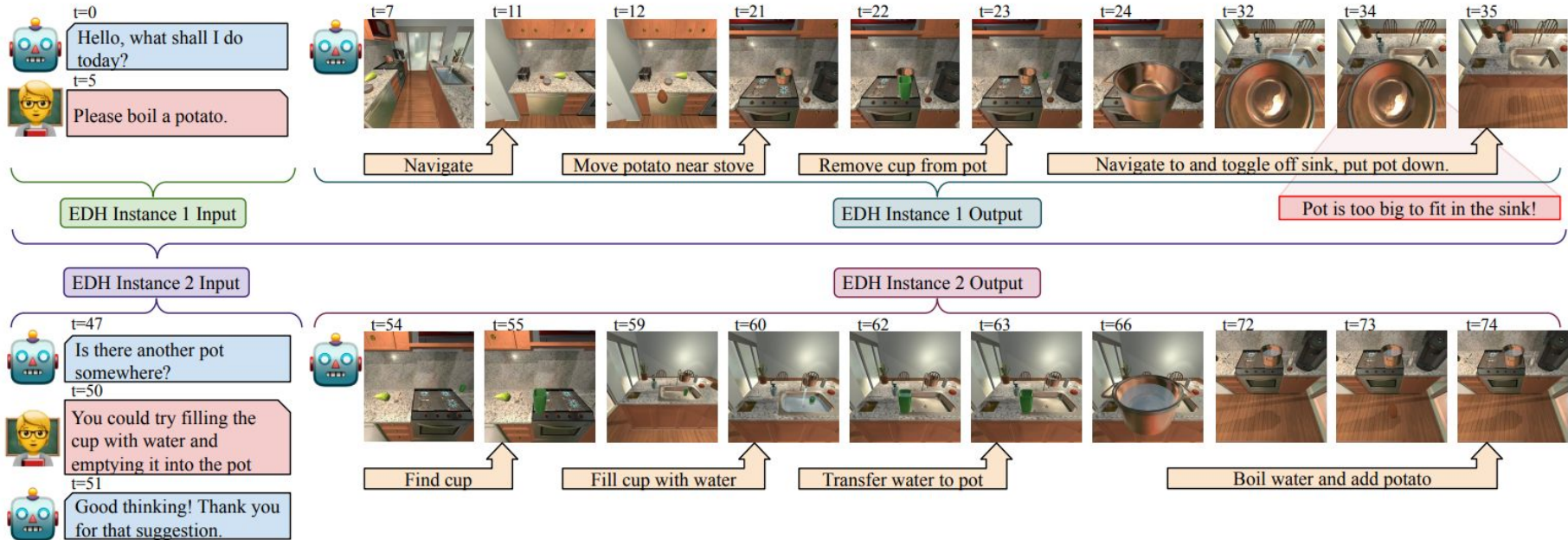
walk on over to the towel drying rack. pick up a dirty red cloth from the towel rack. walk over to the left side of the bathroom sink. turn on the water to rinse the dirty red cloth and pick it back up again. walk back over to the towel drying rack. place the clean cloth on the drying rack.



Datasets (TEACH)

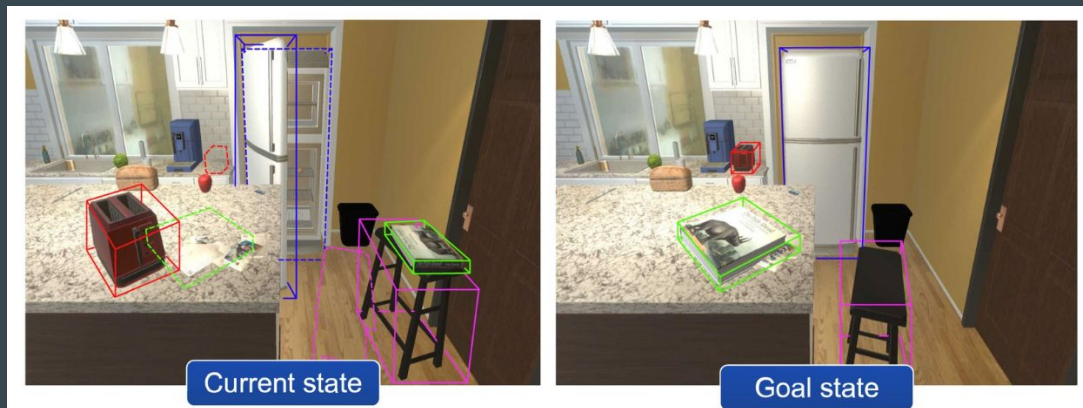
- embodied task completion
- simulated environment
- natural language **dialogue**
 - leader and follower
 - high and low level instructions
- metrics
 - EDH (Execution from History)
 - TfD (Trajectory from Dialogue)
 - TATC (Two Agent Task Completion)





Datasets (Other)

- Rearrangement
 - CVPR'22 Embodied AI Workshop
 - object state manipulation



- ObjectNav
 - CVPR'21 Embodied AI Workshop
 - navigation in simulated environment



Gymnasium (formerly OpenAI Gym)

- similar to AI2THOR
 - games
 - atari, classic board/card games
 - simple 2D environments
 - RL
 - limited dialogue options

Datasets (CerealBar)

- leader and follower setup
 - different abilities
- path planning component
- virtual environment
- metrics
 - sequence accuracies
 - state accuracies
 - points

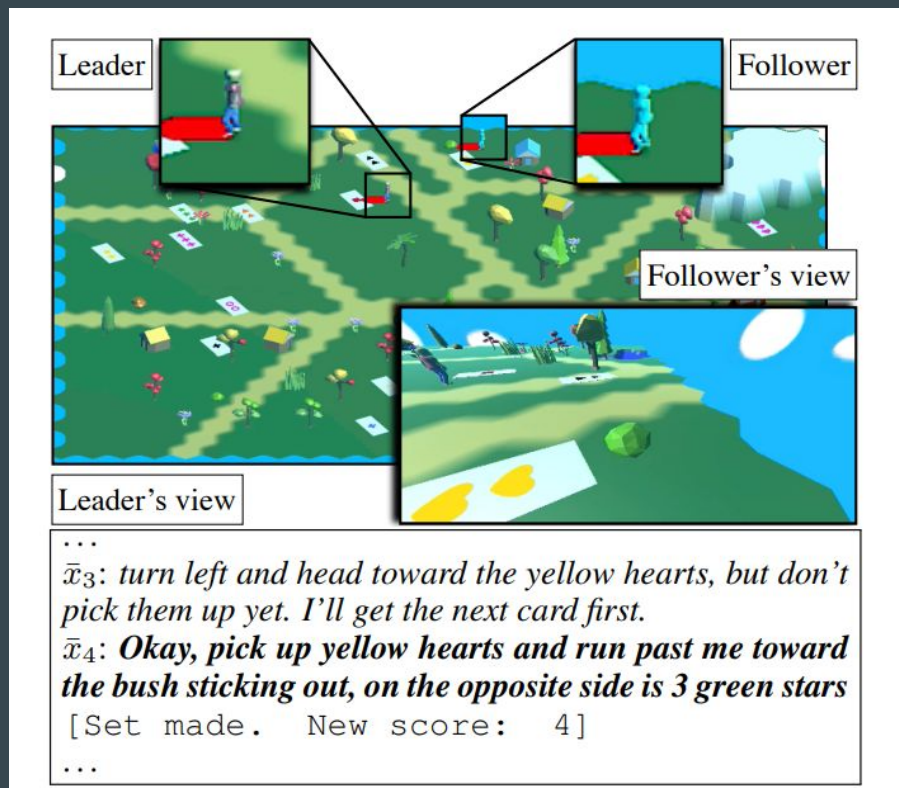




Figure 3: The CEREALBAR leader gameplay interface.

Plan distributions

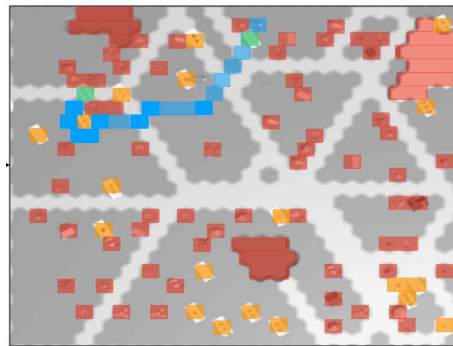
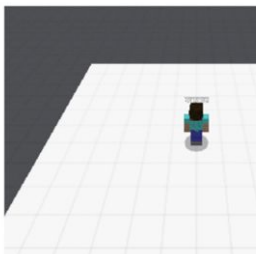


Figure 4: The CEREALBAR follower gameplay interface.

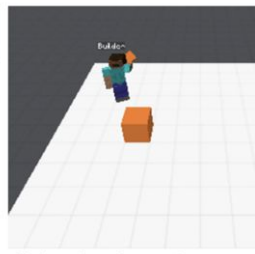
Datasets (MDC)

- leader and follower setup
 - differing abilities
- tasks
 - representing environment
 - producing dialogue
 - predicting actions
- contact:
rsidhu3@illinois.edu



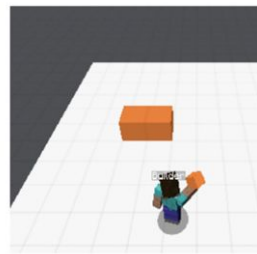
A: go to the middle and place an orange block two spaces to the left

(a)



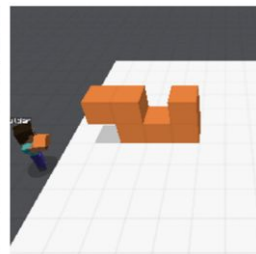
*B: (puts down 1 orange)
A: now make a staircase with 2 stairs left and 2 right with orange*

(b)



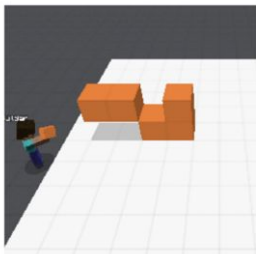
*B: (puts down 1 orange)
A: so it will look like a v*

(c)



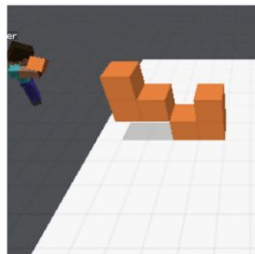
B: (puts down 4 orange)

(d)



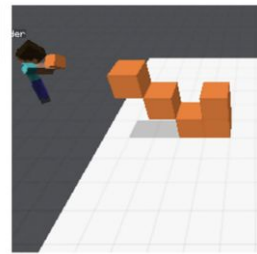
B: (removes 1 orange, creating a floating section)

(e)



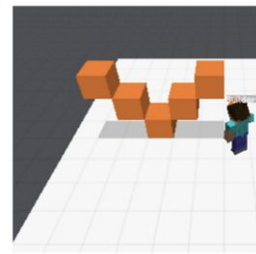
B: (places 1 orange)

(f)



B: (removes 1 orange, creating a floating block)

(g)



B: (follows similar pattern to complete the shape)

(h)

Datasets (general)

- look for
 - API (for video game based datasets)
 - dialogue
 - multiple agents/players
 - clear/quantifiable goal
 - Vision and Language Navigation (VLN) tasks
- feel free to reach out if you're not sure